

Binary Search Trees

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Binary Search Trees = BST

Expected Time Complexity (Average case)

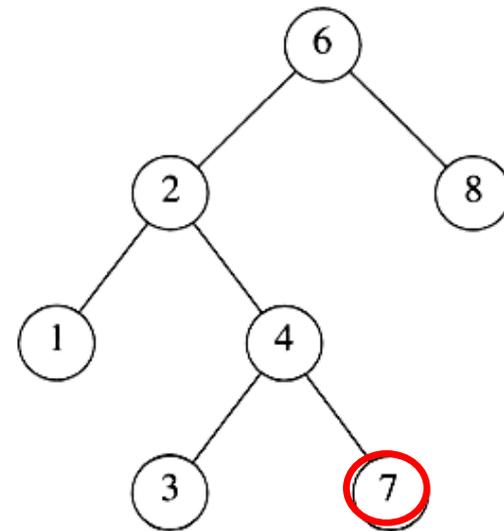
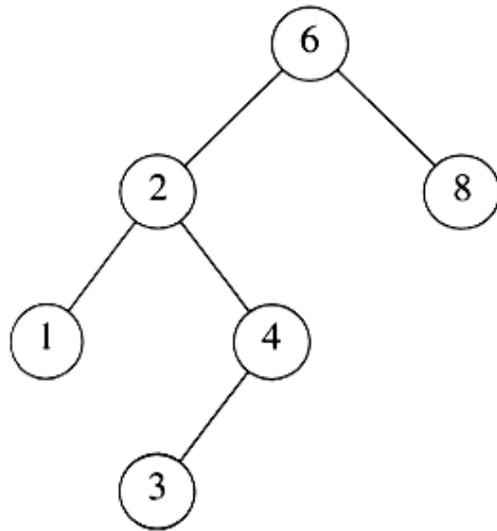
Operation	Binary Search Tree	Array-based List	Linked List
Search	$O(\log N)^*$	-	$O(N)$
Insert	$O(\log N)^*$	$O(N)$	-
Delete	$O(\log N)^*$	$O(N)$	$O(N)$

A BST is a data structure that performs searching, insertion and deletion, efficiently.

Binary Search Tree

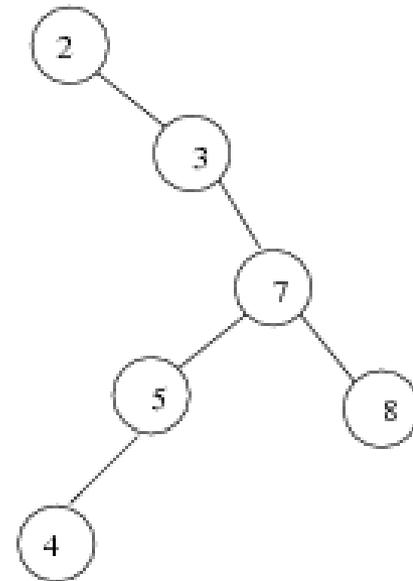
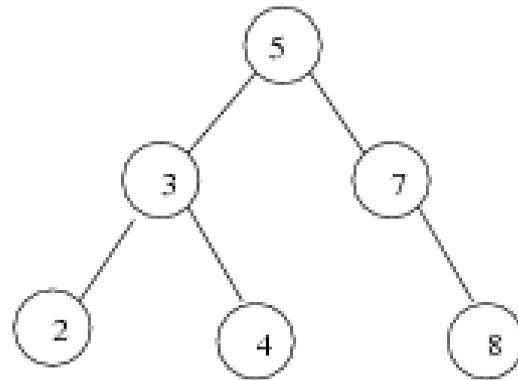
- A binary tree.
- For every node x , all keys in the left subtree of x are smaller than that in x .
- For every node x , all keys in the right subtree of x are greater than that in x .
- The left and right subtrees are also binary search trees.

Examples



More examples

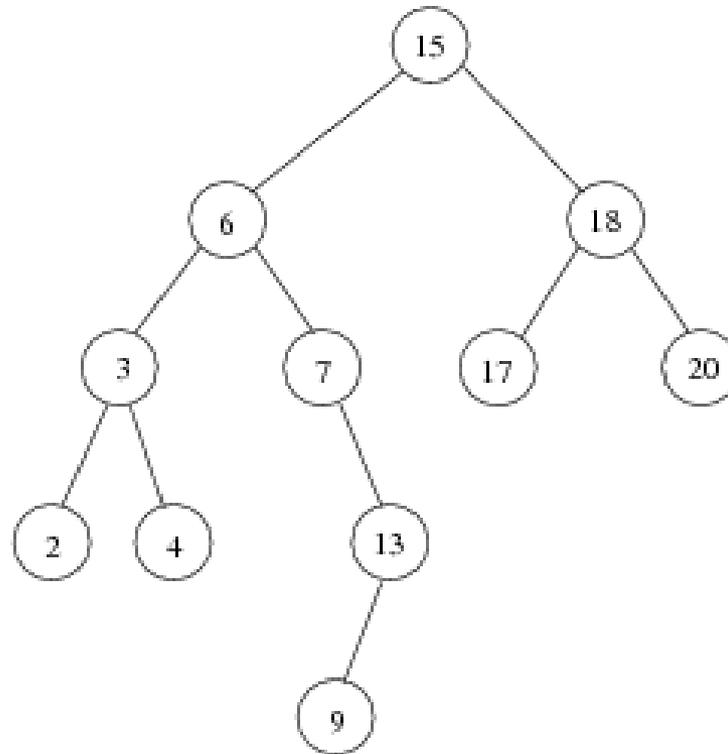
Two binary search trees representing the same set:



- Average depth of a node is $O(\log N)$; maximum depth of a node is $O(N)$

In-order traversal of BST

- Print out all the keys in sorted order



Inorder: 2, 3, 4, 6, 7, 9, 13, 15, 17, 18, 20

Implementing a node in BST

Class Node

```
{  
    Node * left;  
    int data;  
    Node * right;  
}
```

Implementing BST

Class BST

{Public:

BST();

~BST();

int NumberOfNodes();

Node * succ(Node * t);

Node * pred(Node * t);

.....

Node *search(int item);

void insert(int x);

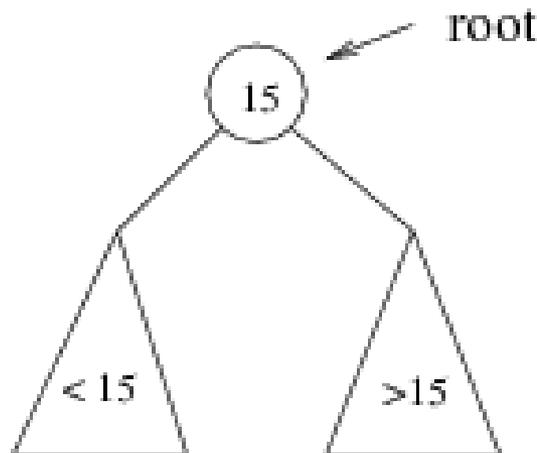
void delete(int key);

Private: Node * root

}

Searching BST

- If we are searching for 15, then we are done.
- If we are searching for a key < 15 , then we should search in the left subtree.
- If we are searching for a key > 15 , then we should search in the right subtree.



Searching BST

```
Node * search (int item)
```

```
{
```

```
Node *r=root;
```

Example: Search for 9 ...

```
while (r) {
```

```
    if (item == r->data) return r;
```

```
    if (item < r->data)
```

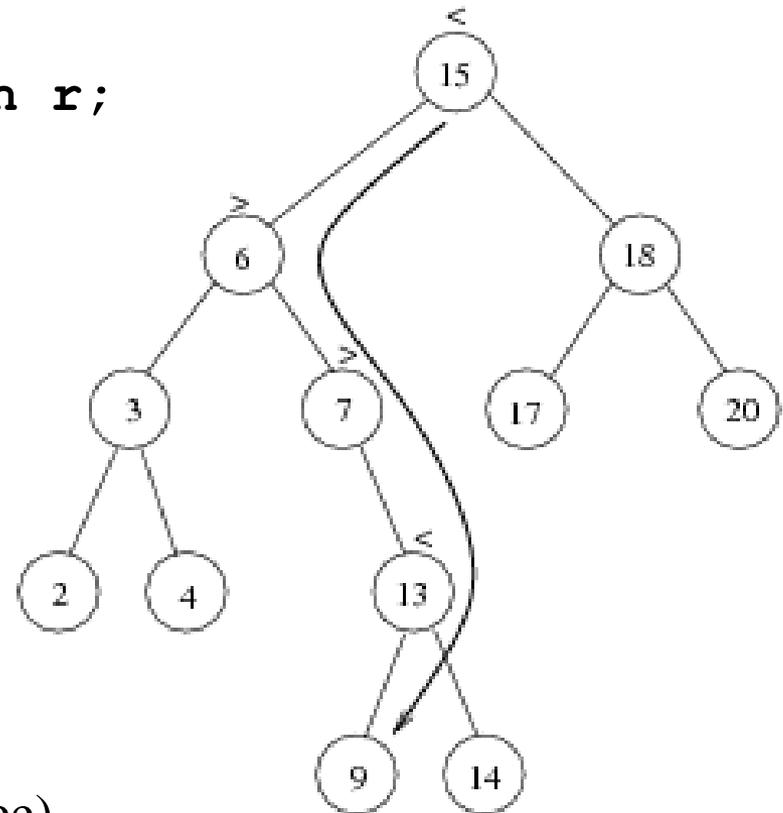
```
        r = r->left;
```

```
    else r = r->right;
```

```
}
```

```
return NULL;
```

```
}
```

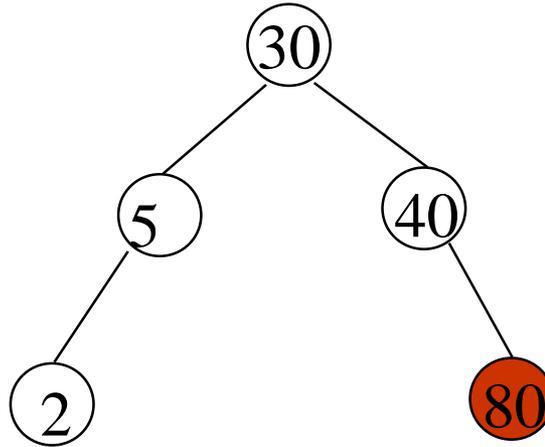
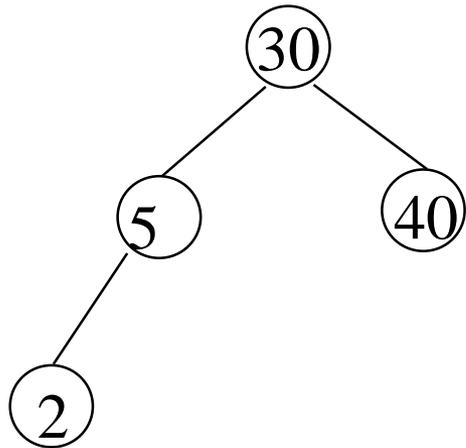


■ Time complexity:

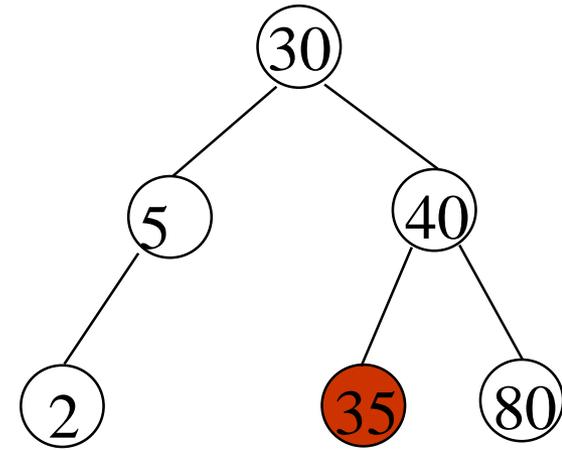
-Average and Worst cases: $O(\text{height of the tree})$

-Best case: $O(1)$

Inserting a Node in Binary Search Tree



Insert 80



Insert 35

Insert

Concept:

- Proceed down tree as in search
- If new key not found, then insert a new node at last spot traversed

Time complexity:

- Average and Worst cases:
 $O(\text{Height of the tree})$
- Best case: $O(1)$

```
void insert(int x)
{
    Node *t=root;
    if ( t == NULL ) {
        t = new Node(x);
    }
    else if (x < t->data) {
        insert( x, t->left );
    }
    else if (x > t->data) {
        insert( x, t->right );
    }
    else {
        // duplicate
        cout<< "The item is already available";
    }
}
```

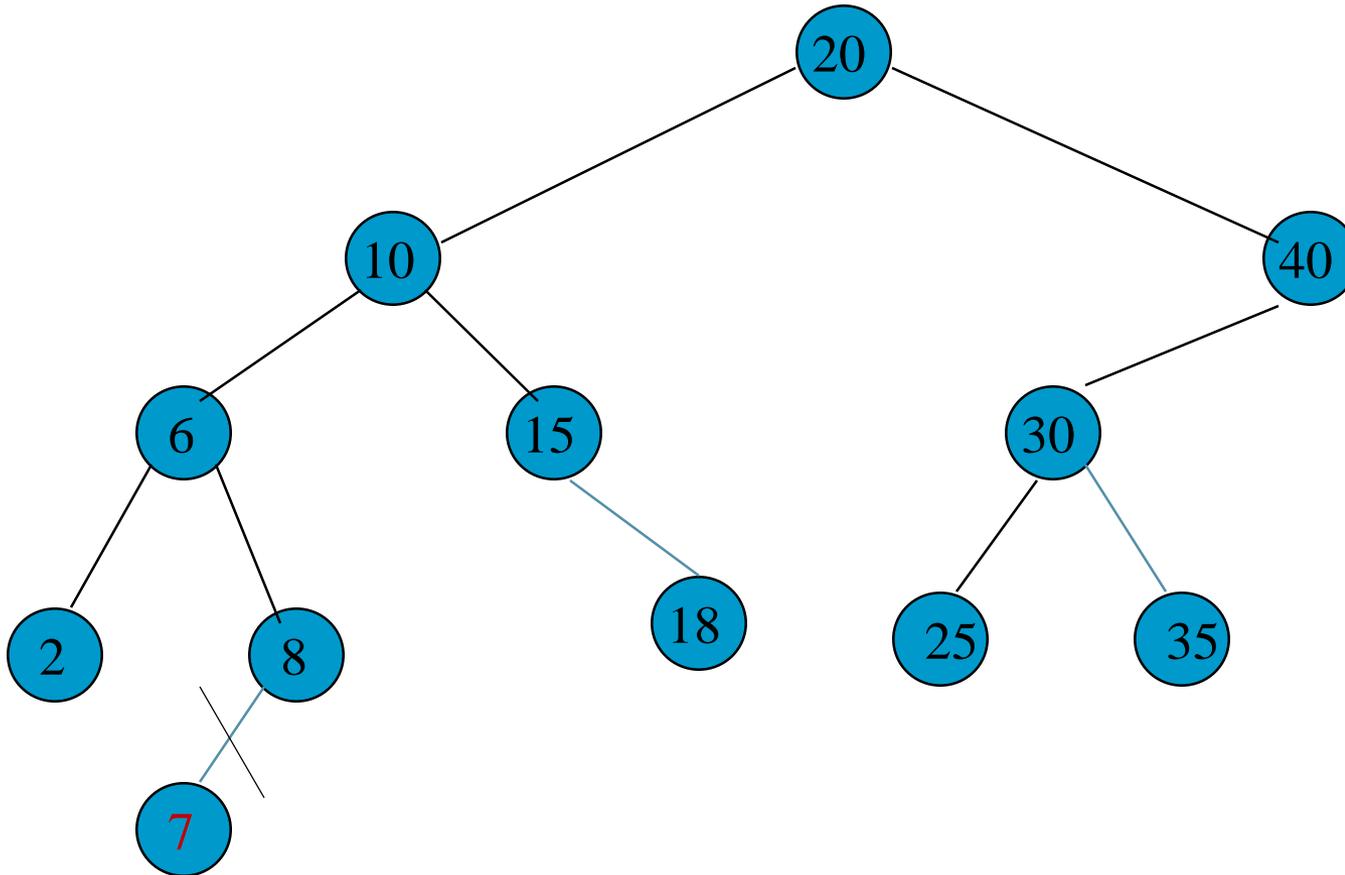
Delete a Node in Binary Search Tree()

- When we delete a node, we need to consider how we take care of the children of the deleted node.
- This has to be done such that the property of the **search tree** is maintained.

Four cases:

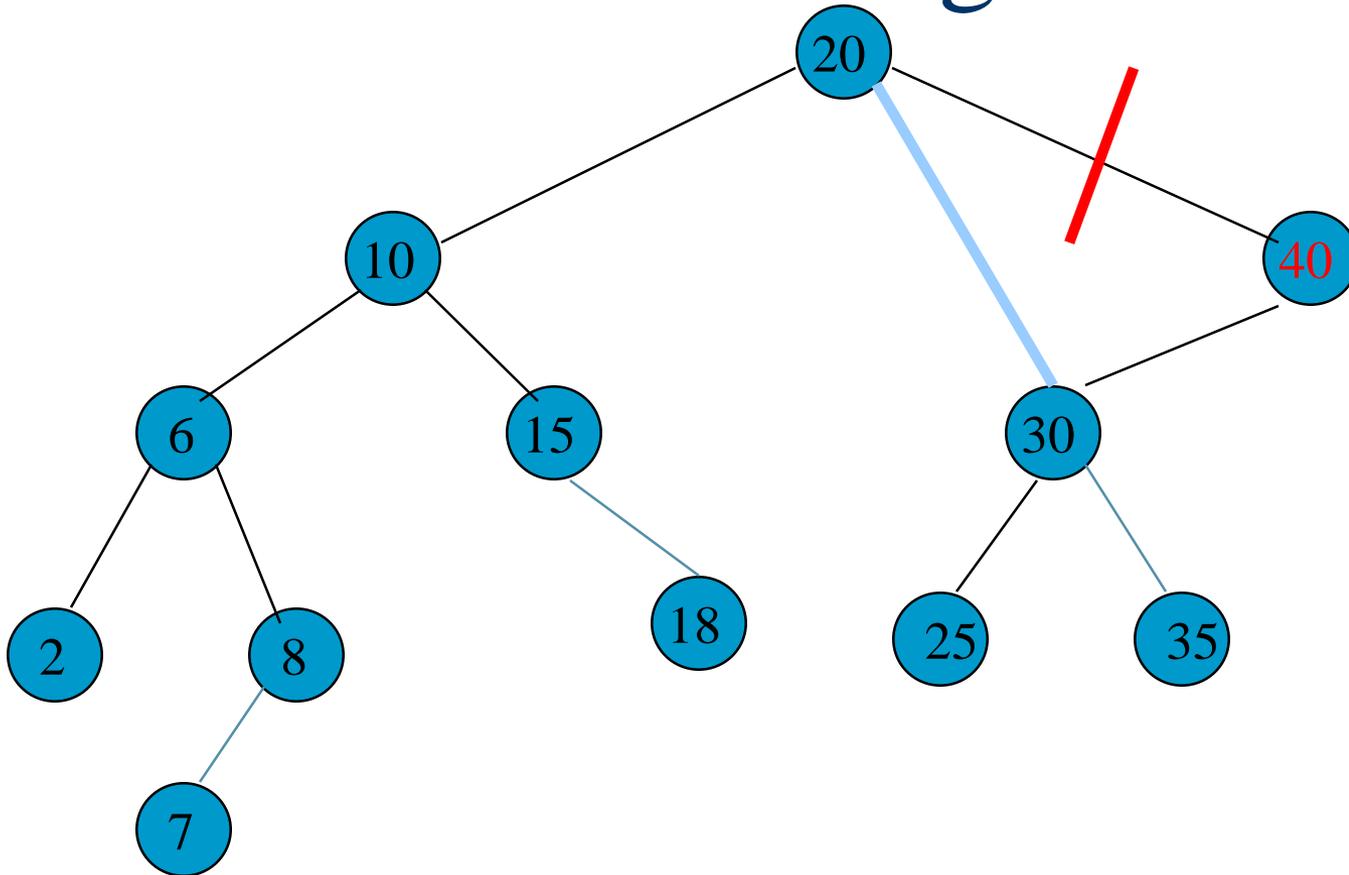
- No node with the key.
- Key is in a leaf.
- Key is in a degree 1 node.
- Key is in a degree 2 node.

Delete From A Leaf



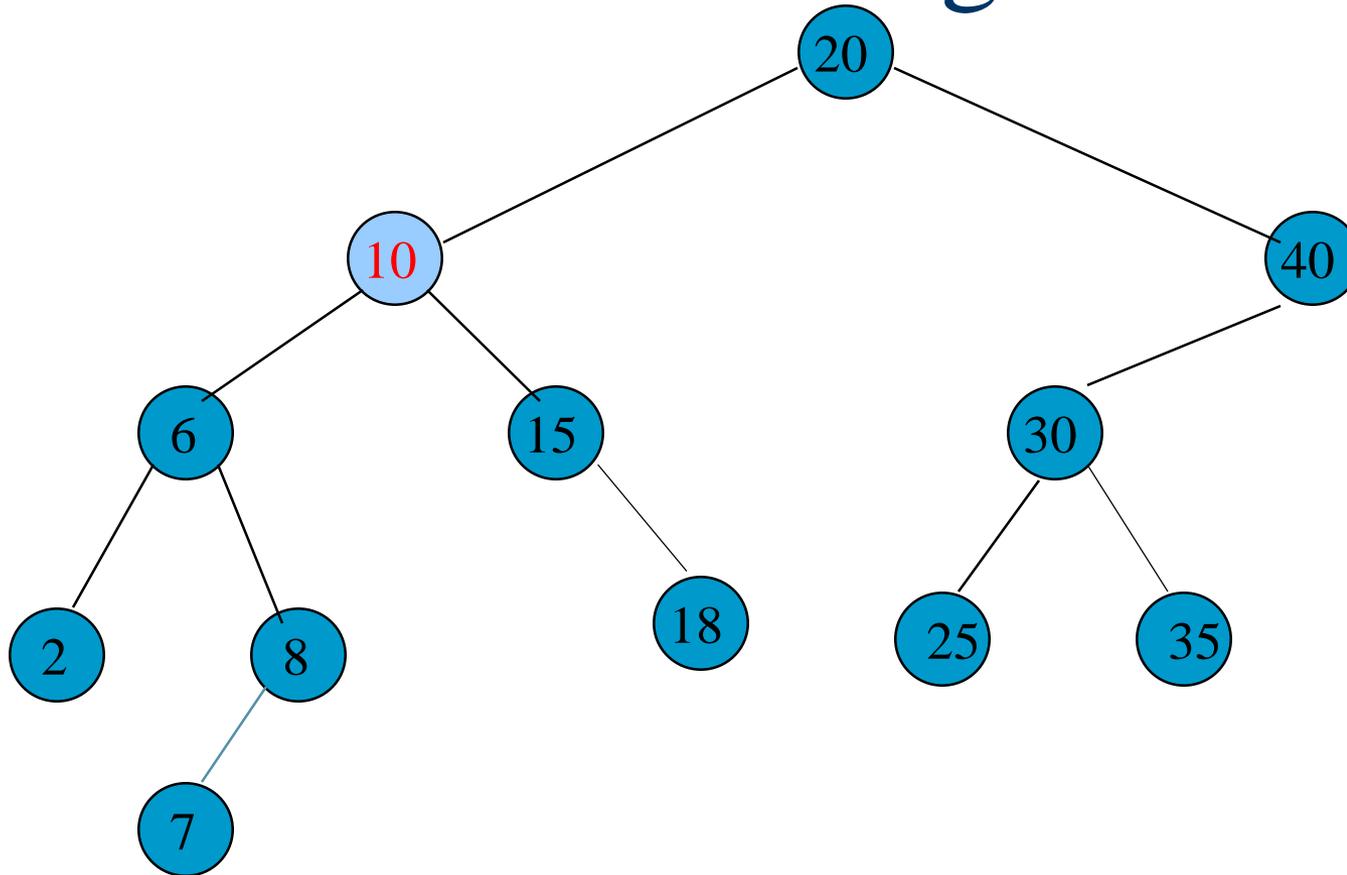
Delete a leaf element. key = 7

Delete From A Degree 1 Node



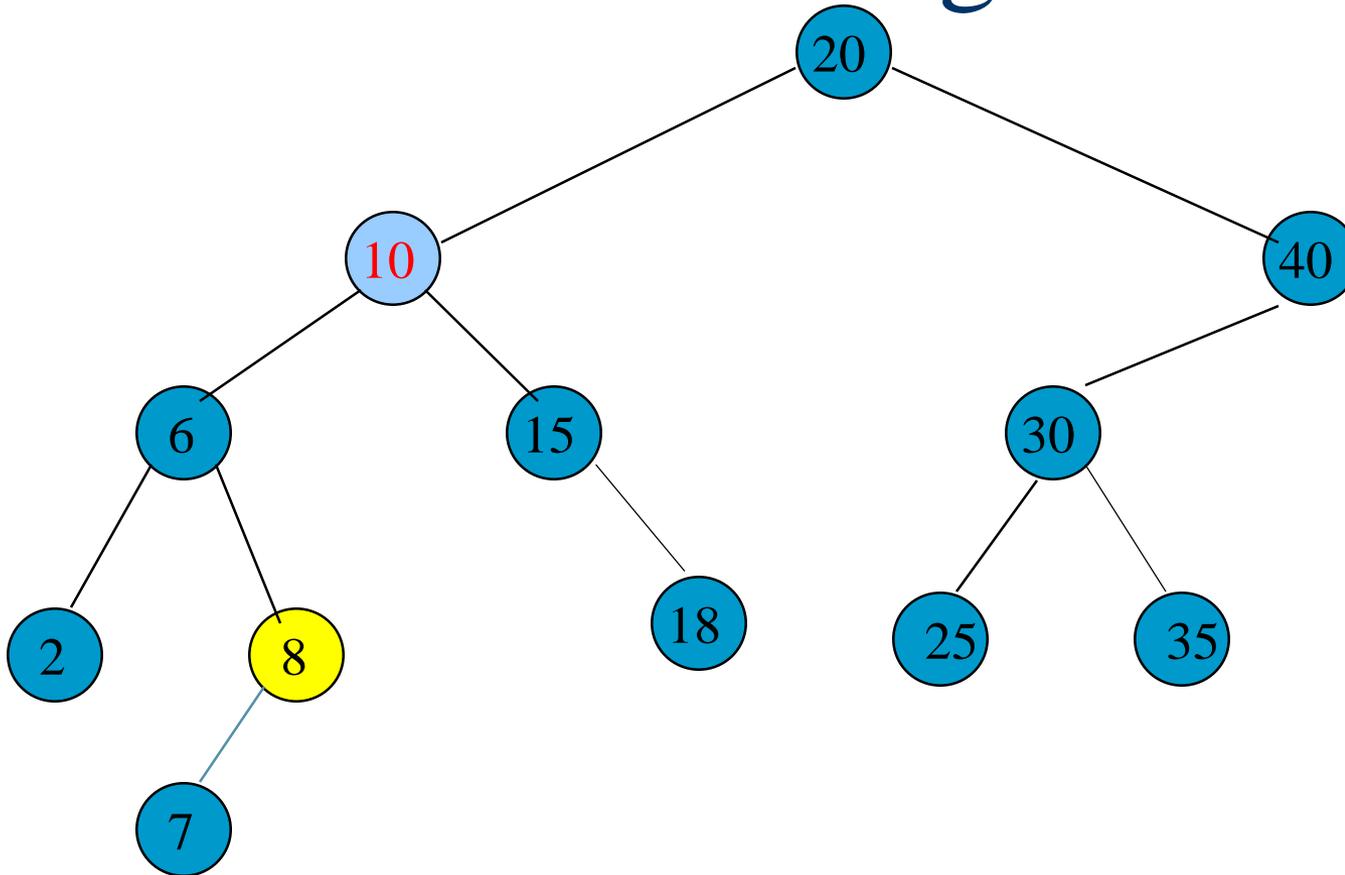
key = 40

Delete From A Degree 2 Node



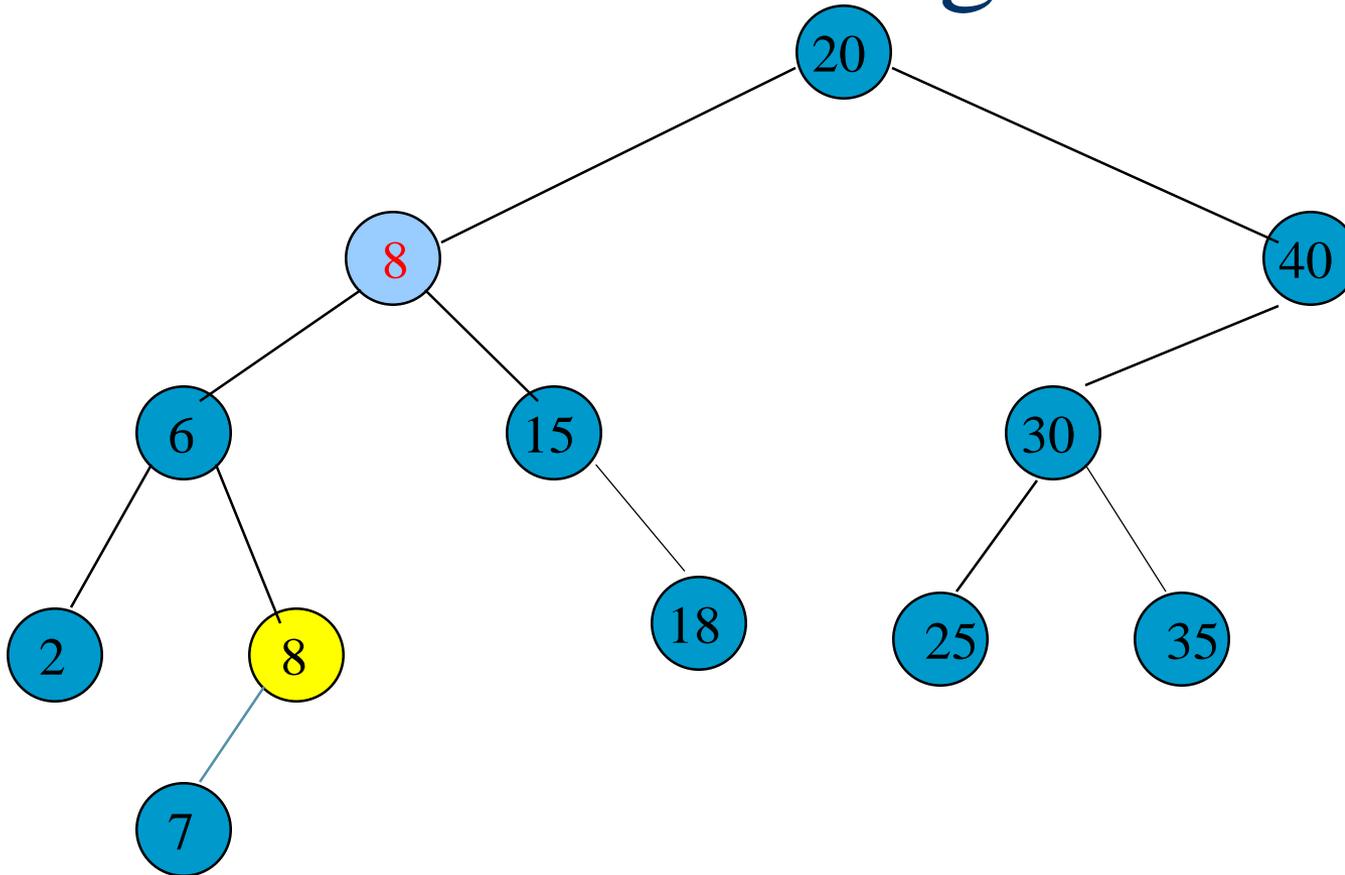
Replace with largest key in left subtree (or smallest in right subtree).

Delete From A Degree 2 Node



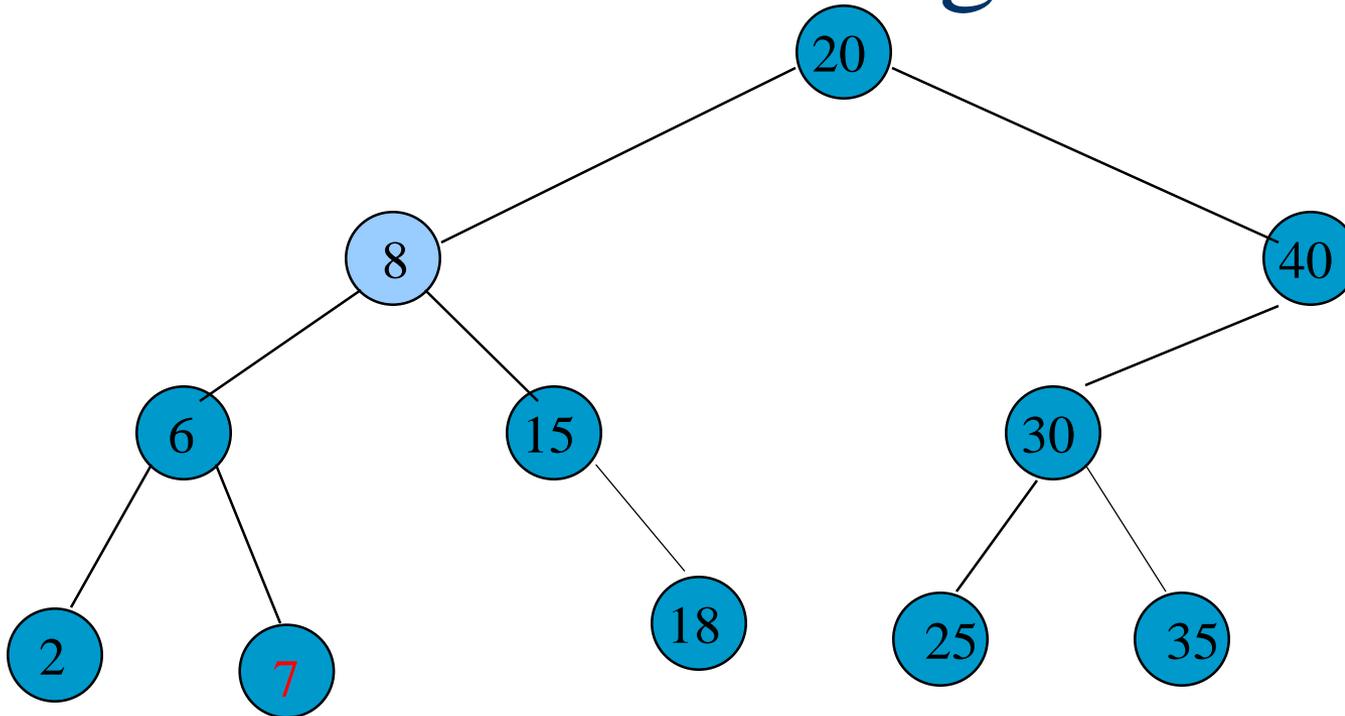
Replace with largest key in left subtree (Rightmost element) or smallest in right subtree (leftmost element).

Delete From A Degree 2 Node



Replace with largest key in left subtree (or smallest in right subtree).

Delete From A Degree 2 Node



Replace with largest key in left subtree (or smallest in right subtree).

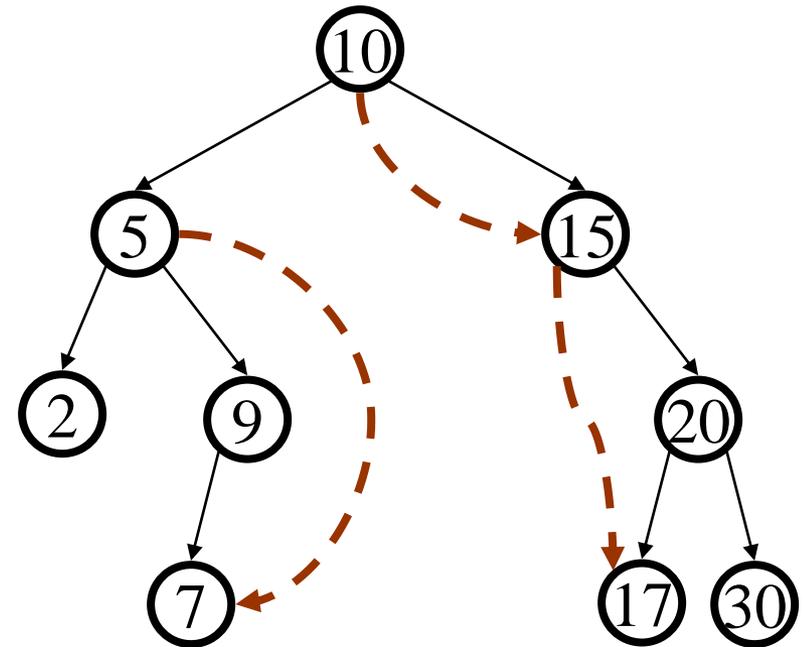
Delete Algorithm

```
void delete(int key) {
    Node * handle=search(key);
    Node * toDelete = handle;
    if (handle != NULL) {
        if (handle->left == NULL) {           // Leaf or one child
            handle = handle->right;
            delete toDelete;
        } else if (handle->right == NULL) { // One child
            handle = handle->left;
            delete toDelete;
        } else {                             // Two children
            successor = succ(toDelete);
            handle->data = successor->data;
            delete(successor->data);
        }
    }
}
```

Successor Node

Next larger node
in this node's subtree

```
Node * succ(Node * t) {  
    if (t->right == NULL)  
        return NULL;  
    else  
        return min(t->right);  
}
```



Applications of BST

- Removing duplicate elements from a list
- Sorting a list

Conclusion

Binary Search Trees are fast if they're balanced:

What matters?

- Problems occur when one branch is **much longer** than another
- i.e. when tree is **out of balance**